

The n by n **Hilbert matrix** is defined by

$$H_n = \begin{pmatrix} 1 & 1/2 & \dots & 1/n \\ 1/2 & 1/3 & \dots & 1/(n+1) \\ \vdots & \vdots & \ddots & \vdots \\ 1/n & 1/(n+1) & \dots & 1/(2n-1) \end{pmatrix};$$

the row i , column j entry is $h_{ij} = 1/(i+j-1)$. This matrix arises naturally in several contexts, e.g., in approximation theory.

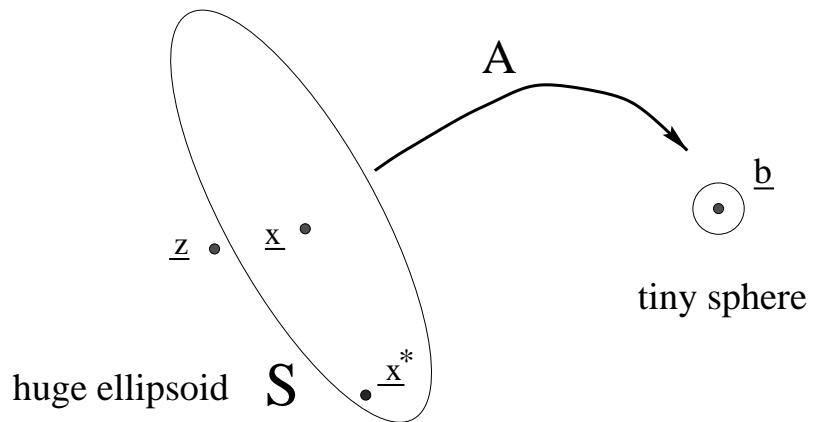
Consider the system $A\underline{x} = \underline{b}$ where $A = H_n$ and \underline{b} is the vector with $b_i = \sum_{j=1}^n h_{ij}$. Clearly this system has solution vector \underline{x} whose components are all ones.

The matrix $A = H_n$ is notorious for propagating roundoff errors in Gaussian elimination (we will see some reasons for this later). The following outputs are from my program to compute the *LUP* factorization of H_n using partial pivoting, and then, the solution to $A\underline{x} = \underline{b}$ by forward-substitution (solution of $Ly = \underline{b}(p)$) and backsolving $U\underline{x} = \underline{y}$. We denote the computed solution by \underline{x}^* and the error vector as $\underline{e} \equiv \underline{x} - \underline{x}^*$. Finally the **residual** vector is defined to be

$$\underline{r} = A\underline{e} = A(\underline{x} - \underline{x}^*) = \underline{b} - A\underline{x}^*.$$

Notice that in a typical, real computational situation we would NOT know \underline{e} because we do not know the solution \underline{x} , but we always DO KNOW \underline{r} from the given data and our computed solution. However In the examples that follow I carefully chose the right-hand sides \underline{b} to force the unknown solution \underline{x} to be the vector of ones.

The following pages of output show that even though \underline{e} may be large (i.e., its length $\|\underline{e}\| = \sqrt{e_1^2 + \dots + e_n^2}$ is large), the residual vector is small. This seems to be a property of the kind of errors committed by Gaussian elimination.



The picture is meant to convey the idea that for certain matrices A (like H_n , e.g.) (i) the points \underline{z} that A maps “near” to \underline{b} can lie in a large set S (with points FAR from $\underline{x} = A^{-1}\underline{b}$); (ii) Gaussian-Elimination computes a solution $\underline{x}^* \in S$ (so it has small residual, even if it may have a large error); (iii) there are points $\underline{z} \notin S$ that are close to $\underline{x} = A^{-1}\underline{b}$ (small error) but still have large residuals (Gaussian elimination does not seem to find such points).

p	compact	LU	L	U	
1	1.0000	0.5000	0.3333	1.0000 0.0000 0.0000	1.0000 0.5000 0.3333
2	0.5000	0.0833	0.0833	0.5000 1.0000 0.0000	0.0000 0.0833 0.0833
3	0.3333	1.0000	0.0056	0.3333 1.0000 1.0000	0.0000 0.0000 0.0056

y	x*	e	r
0.183333E+01	0.999999E+00	0.953674E-06	0.298023E-07
0.166667E+00	0.100001E+01	-0.548363E-05	0.298023E-07
0.555554E-02	0.999995E+00	0.536442E-05	0.447035E-07

$|e| = 0.773024E-05$

p	compact	LU			
1	1.0000	0.5000	0.3333	0.2500	0.2000
2	0.5000	0.0833	0.0833	0.0750	0.0667
5	0.2000	0.8000	0.0095	0.0150	0.0178
3	0.3333	1.0000	0.5833	-.0004	-.0008
4	0.2500	0.9000	0.8750	0.6428	0.0000

y	x*	e	r
0.228333E+01	0.100007E+01	-0.749826E-04	0.149012E-07
0.308333E+00	0.998680E+00	0.132036E-02	0.298023E-07
0.423016E-01	0.100548E+01	-0.548434E-02	-0.447035E-07
-0.126313E-02	0.991939E+00	0.806147E-02	-0.447035E-07
-0.113896E-04	0.100386E+01	-0.386322E-02	-0.149012E-07

$|e| = 0.105707E-01$

p compact LU

1	1.0000	0.5000	0.3333	0.2500	0.2000	0.1667	0.1429
2	0.5000	0.0833	0.0833	0.0750	0.0667	0.0595	0.0536
7	0.1429	0.6429	0.0099	0.0161	0.0195	0.0213	0.0221
3	0.3333	1.0000	0.5600	- .0007	- .0014	- .0020	- .0024
5	0.2000	0.8000	0.9600	0.6429	0.0000	- .0001	- .0001
4	0.2500	0.9000	0.8400	0.9643	0.8439	0.0000	0.0000
6	0.1667	0.7143	1.0000	0.2976	0.6257	- .5555	0.0000

y x* e r

0.259286E+01	0.100090E+01	-0.903249E-03	0.745058E-07
0.421429E+00	0.967215E+00	0.327848E-01	0.149012E-07
0.888072E-01	0.129571E+01	-0.295714E+00	0.447035E-07
-0.647800E-02	-0.945102E-01	0.109451E+01	0.447035E-07
-0.260744E-03	0.293098E+01	-0.193098E+01	0.745058E-07
0.351676E-05	-0.617661E+00	0.161766E+01	0.000000E+00
-0.165790E-06	0.151771E+01	-0.517712E+00	0.372529E-07

|e| = 0.281070E+01

p compact LU

1	1.0000	0.5000	0.3333	0.2500	0.2000	0.1667	0.1429	0.1250	0.1111
2	0.5000	0.0833	0.0833	0.0750	0.0667	0.0595	0.0536	0.0486	0.0444
7	0.1429	0.6429	0.0099	0.0161	0.0195	0.0213	0.0221	0.0223	0.0222
3	0.3333	1.0000	0.5600	- .0007	- .0014	- .0020	- .0024	- .0028	- .0030
9	0.1111	0.5333	0.9503	- .4242	0.0000	0.0001	0.0002	0.0003	0.0004
4	0.2500	0.9000	0.8400	0.9643	- .6159	0.0000	0.0000	0.0000	0.0000
5	0.2000	0.8000	0.9600	0.6429	- .7298	0.8505	0.0000	0.0000	0.0000
6	0.1667	0.7143	1.0000	0.2976	- .4566	0.3754	0.1487	0.0000	0.0000
8	0.1250	0.5833	0.9800	- .2386	0.5076	- .1102	- .3953	- .3756	0.0000

y x* e r

0.282897E+01	0.998807E+00	0.119287E-02	0.178814E-06
0.514484E+00	0.104947E+01	-0.494668E-01	-0.596046E-07
0.133351E+00	0.522337E+00	0.477663E+00	0.119209E-06
-0.122726E-01	0.258982E+01	-0.158982E+01	0.000000E+00
0.104370E-02	0.210264E+00	0.789736E+00	0.596046E-07
0.619291E-04	-0.551675E+01	0.651675E+01	-0.298023E-07
0.134884E-05	0.161007E+02	-0.151007E+02	0.596046E-07
0.257875E-06	-0.119670E+02	0.129670E+02	0.178814E-06
0.845820E-07	0.501332E+01	-0.401332E+01	0.894070E-07

|e| = 0.214040E+02

A similar phenomenon occurs in the computation of A^{-1} . When A is the Hilbert matrix we make large errors in the computation of (A^{-1}) . Here is the true inverse of H_7 , the 7 by 7 Hilbert matrix: $H_7^{-1} =$

[49	-1176	8820	-29400	48510	-38808	12012]
[]
[-1176	37632	-317520	1128960	-1940400	1596672	-504504]
[]
[8820	-317520	2857680	-10584000	18711000	-15717240	5045040]
[]
[-29400	1128960	-10584000	40320000	-72765000	62092800	-20180160]
[]
[48510	-1940400	18711000	-72765000	133402500	-115259760	37837800]
[]
[-38808	1596672	-15717240	62092800	-115259760	100590336	-33297264]
[]
[12012	-504504	5045040	-20180160	37837800	-33297264	11099088]

and here is what I computed by following the efficient algorithm using Gauss-Jordan reduction on the LUP factorization, answers rounded to the nearest integer (A^* is the computed inverse of H_7). $A^* =$

37.	-680.	3997.	-10499.	13635.	-8513.	2021.
-682.	17701.	-123698.	369784.	-540135.	380627.	-103545.
4031.	-124267.	979226.	-3228815.	5148214.	-3941198.	1162847.
-10673.	373653.	-3244812.	11590284.	-19798362.	16111001.	-5023300.
14014.	-549598.	5200422.	-19887368.	35931044.	-30652272.	9951588.
-8880.	390447.	-4002181.	16249666.	-30765518.	27254454.	-9128023.
2152.	-107212.	1187148.	-5085478.	10019309.	-9154415.	3142867.

Though the relative errors in A^* are enormous, the product $(H_7)(A^*)$ is not far from the identity matrix.