

CS534: Introduction to Computer Vision  
Fourier Transform

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## Outlines

- Fourier Series and Fourier integral
- Fourier Transform (FT)
- Discrete Fourier Transform (DFT)
- Aliasing and Nyquist Theorem
- 2D FT and 2D DFT
- Application of 2D-DFT in imaging
- Inverse Convolution
- Discrete Cosine Transform (DCT)

Sources:

- Forsyth and Ponce, Chapter 7
- Burger and Burge “Digital Image Processing” Chapter 13, 14, 15
- Fourier transform images from Prof. John M. Brayer @ UNM  
<http://www.cs.unm.edu/~brayer/vision/fourier.html>

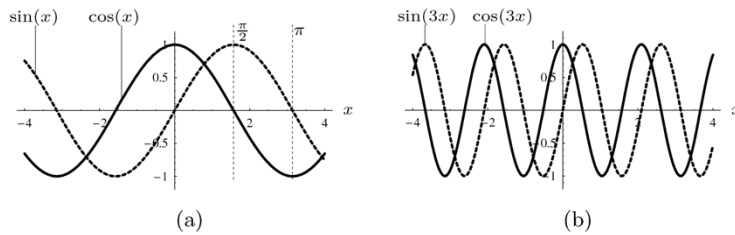
## Basics

- Sine and Cosine functions are periodic  
 $\cos(x) = \cos(x + 2\pi) = \cos(x + 4\pi) = \dots = \cos(x + k \cdot 2\pi)$
- Angular Frequency ( $\omega$ ) and Amplitude ( $a$ )  
 $a \cdot \cos(\omega x)$  and  $a \cdot \sin(\omega x)$
- Angular Frequency ( $\omega$ ): number of oscillations over the distance  $2\pi$   
 $T$ : the time for a complete cycle

$$T = \frac{2\pi}{\omega}$$

- Common Frequency  $f$ : number of oscillation in a unit time

$$f = \frac{1}{T} = \frac{\omega}{2\pi} \quad \text{or} \quad \omega = 2\pi f$$

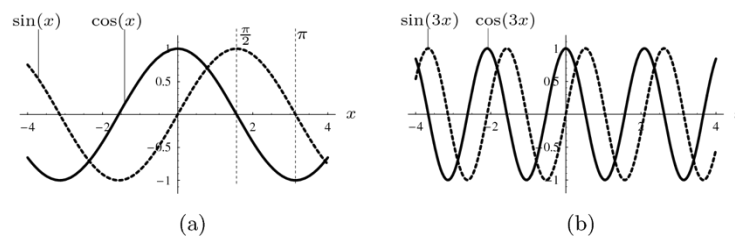


## Basics

- Phase: Shifting a cosine function along the x axis by a distance  $\varphi$  change the phase of the cosine wave.  $\varphi$  denotes the phase angle

$$\cos(x) \rightarrow \cos(x - \varphi)$$

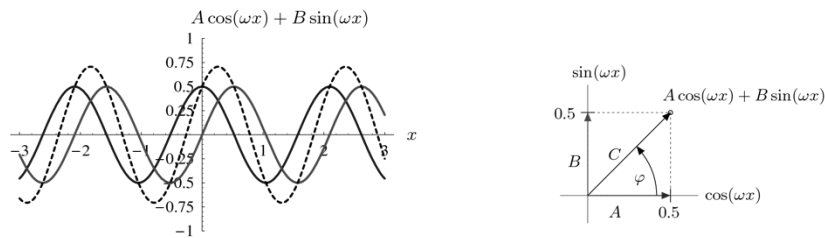
$$\sin(\omega x) = \cos\left(\omega x - \frac{\pi}{2}\right)$$



- Adding cosines and sines with the same frequency results in another sinusoid

$$A \cdot \cos(\omega x) + B \cdot \sin(\omega x) = C \cdot \cos(\omega x - \varphi)$$

$$C = \sqrt{A^2 + B^2} \quad \text{and} \quad \varphi = \tan^{-1}\left(\frac{B}{A}\right)$$



$$e^{i\theta} = e^{i\omega x} = \cos(\omega x) + i \cdot \sin(\omega x)$$

## Fourier Series and Fourier integral

- We can represent any periodic function as sum of pairs of sinusoidal functions- using a basic (fundamental) frequency

$$g(x) = \sum_{k=0}^{\infty} [A_k \cos(k\omega_0 x) + B_k \sin(k\omega_0 x)]$$

- Fourier Integral: any function can be represented as combination of sinusoidal functions with infinitely many frequencies

$$g(x) = \int_0^{\infty} A_{\omega} \cos(\omega x) + B_{\omega} \sin(\omega x) d\omega$$

- Fourier Integral

$$g(x) = \int_0^{\infty} A_{\omega} \cos(\omega x) + B_{\omega} \sin(\omega x) d\omega$$

- How much of each frequency contributes to a given function

$$A_{\omega} = A(\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} g(x) \cdot \cos(\omega x) dx$$

$$B_{\omega} = B(\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} g(x) \cdot \sin(\omega x) dx$$

## Fourier Transform

$$e^{i\theta} = e^{i\omega x} = \cos(\omega x) + i \cdot \sin(\omega x)$$

$$A_{\omega} = A(\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} g(x) \cdot \cos(\omega x) dx$$

$$B_{\omega} = B(\omega) = \frac{1}{\pi} \int_{-\infty}^{\infty} g(x) \cdot \sin(\omega x) dx$$

$$\begin{aligned} G(\omega) &= \sqrt{\frac{\pi}{2}} [A(\omega) - i \cdot B(\omega)] \\ &= \sqrt{\frac{\pi}{2}} \left[ \frac{1}{\pi} \int_{-\infty}^{\infty} g(x) \cdot \cos(\omega x) dx - i \cdot \frac{1}{\pi} \int_{-\infty}^{\infty} g(x) \cdot \sin(\omega x) dx \right] \\ &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot [\cos(\omega x) - i \cdot \sin(\omega x)] dx, \end{aligned}$$

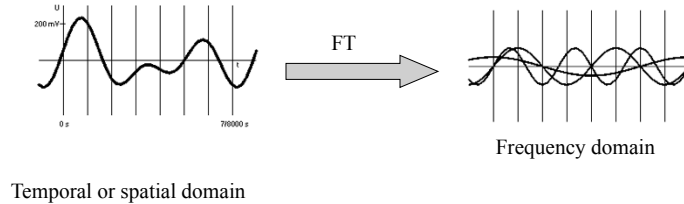
$$\begin{aligned} G(\omega) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot [\cos(\omega x) - i \cdot \sin(\omega x)] dx \\ &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot e^{-i\omega x} dx. \end{aligned}$$

- Fourier transform

$$G(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot [\cos(\omega x) - i \cdot \sin(\omega x)] dx$$
$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot e^{-i\omega x} dx.$$

- Inverse Fourier transform

$$g(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} G(\omega) \cdot [\cos(\omega x) + i \cdot \sin(\omega x)] d\omega$$
$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} G(\omega) \cdot e^{i\omega x} d\omega.$$

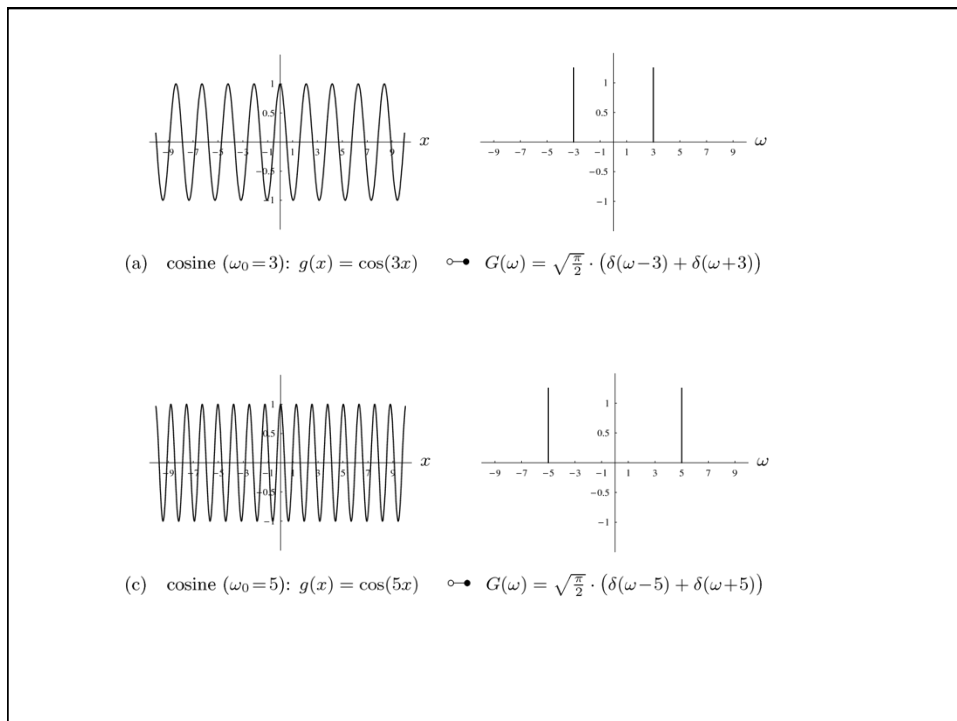


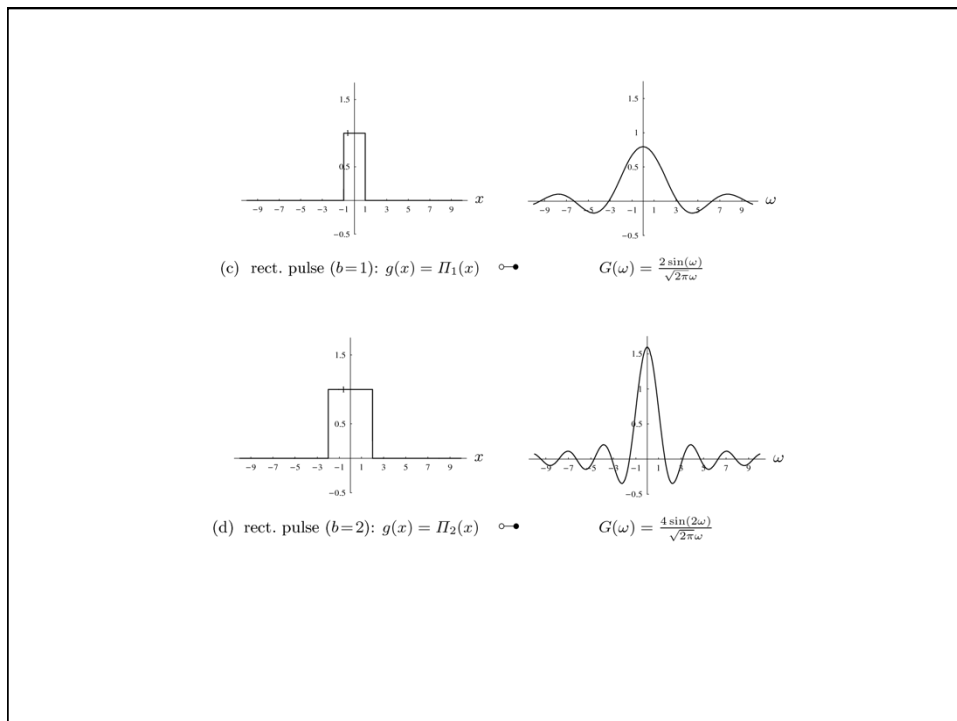
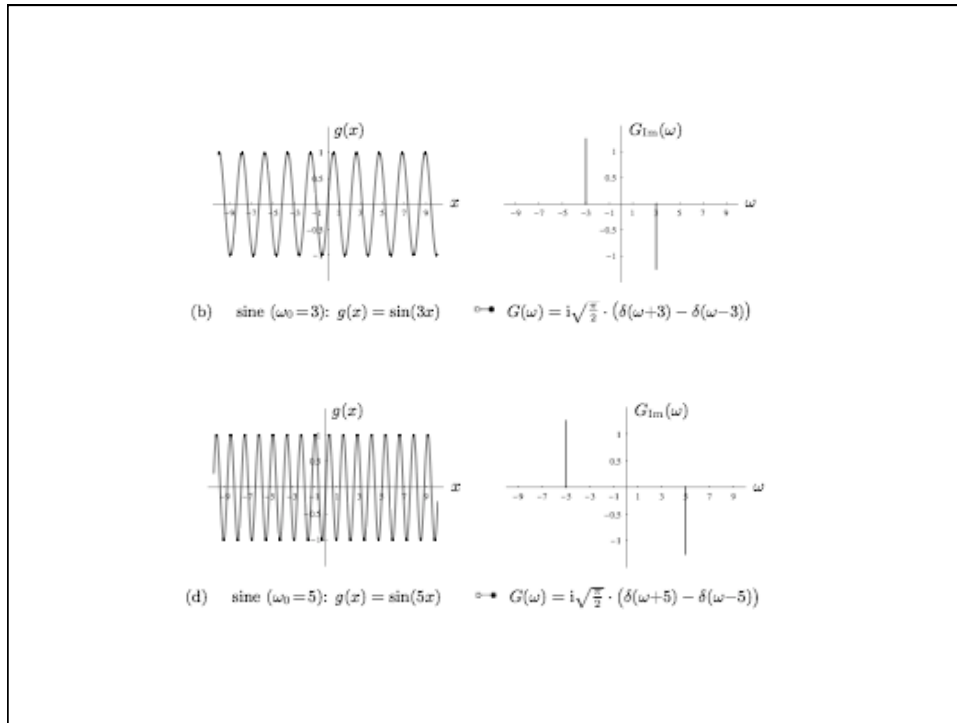
## Fourier Transform

- The forward and inverse transformation are almost similar (only the sign in the exponent is different)
- any signal is represented in the frequency space by its frequency “spectrum”
- The Fourier spectrum is uniquely defined for a given function. The opposite is also true.
- Fourier transform pairs

$$g(x) \circ \bullet G(\omega)$$

Function	Transform Pair $g(x) \leftrightarrow G(\omega)$	Figure
<b>Cosine function</b> with frequency $\omega_0$	$g(x) = \cos(\omega_0 x)$ $G(\omega) = \sqrt{\frac{\pi}{2}} \cdot (\delta(\omega - \omega_0) + \delta(\omega + \omega_0))$	13.3 (a, c)
<b>Sine function</b> with frequency $\omega_0$	$g(x) = \sin(\omega_0 x)$ $G(\omega) = i\sqrt{\frac{\pi}{2}} \cdot (\delta(\omega - \omega_0) - \delta(\omega + \omega_0))$	13.3 (b, d)
<b>Gaussian function</b> of width $\sigma$	$g(x) = \frac{1}{\sigma} \cdot e^{-\frac{x^2}{2\sigma^2}}$ $G(\omega) = e^{-\frac{\sigma^2 \omega^2}{2}}$	13.4 (a, b)
<b>Rectangular pulse</b> of width $2b$	$g(x) = \Pi_b(x) = \begin{cases} 1 & \text{for }  x  \leq b \\ 0 & \text{otherwise} \end{cases}$ $G(\omega) = \frac{2b \sin(b\omega)}{\sqrt{2\pi}\omega}$	13.4 (c, d)

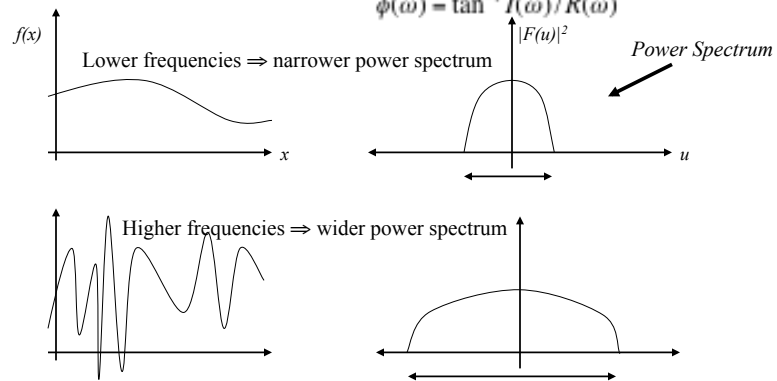




- Since of FT of a real function is generally complex, we use magnitude and phase

$$G(\omega) = R(\omega) + jI(\omega) \quad \Rightarrow \quad |G(\omega)| = (R^2(\omega) + I^2(\omega))^{1/2}$$

$$\phi(\omega) = \tan^{-1} I(\omega) / R(\omega)$$



## Properties

- Symmetry: for real-valued functions

$$G(\omega) = G^*(-\omega)$$

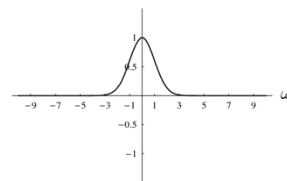
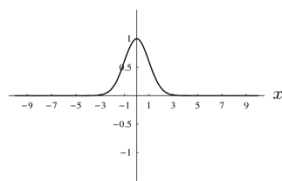
- Linearity

$$c \cdot g(x) \quad \circlearrowright \quad c \cdot G(\omega)$$

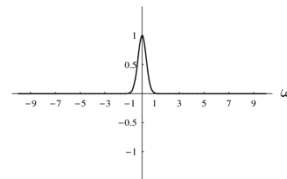
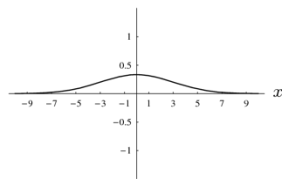
$$g_1(x) + g_2(x) \quad \circlearrowright \quad G_1(\omega) + G_2(\omega)$$

▪ Similarity

$$g(sx) \longleftrightarrow \frac{1}{|s|} \cdot G\left(\frac{\omega}{s}\right)$$



(a) Gauss ( $\sigma=1$ ):  $g(x) = e^{-\frac{x^2}{2}}$   $\longleftrightarrow$   $G(\omega) = e^{-\frac{\omega^2}{2}}$



(b) Gauss ( $\sigma=3$ ):  $g(x) = \frac{1}{3} \cdot e^{-\frac{x^2}{2 \cdot 9}}$   $\longleftrightarrow$   $G(\omega) = e^{-\frac{\omega^2}{2}}$

Important Properties:

- FT and Convolution
- Convolution of two signals is equivalent to multiplying their Fourier spectra

$$g(x) * h(x) \longleftrightarrow G(\omega) \cdot H(\omega)$$

- Multiplying two signals is equivalent to convolving their Fourier spectra

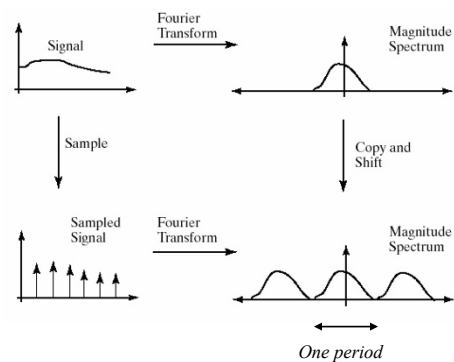
$$g(x) \cdot h(x) \longleftrightarrow G(\omega) * H(\omega)$$

- FT of a Gaussian with sd= $\sigma$  is a Gaussian with sd= $1/\sigma$

Fourier Transform of discrete signals

- If we discretize  $f(x)$  using uniformly spaced samples  $f(0), f(1), \dots, f(N-1)$ , we can obtain FT of the sampled function

- Important Property:  
Periodicity  $F(m) = F(m+N)$



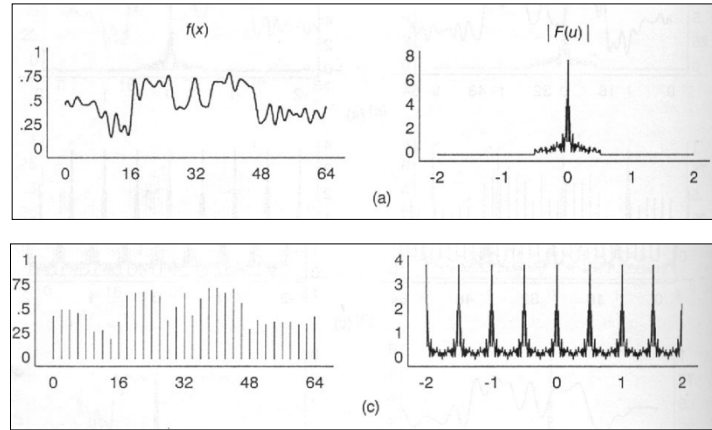
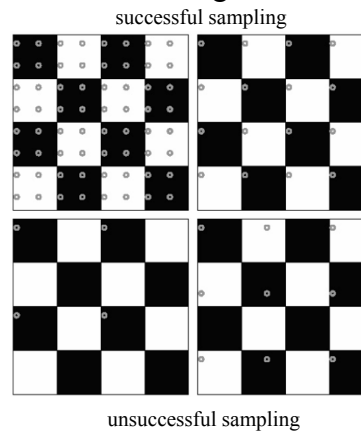
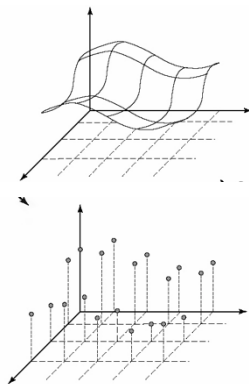


Image from *Computer Graphics: Principles and Practice*  
by Foley, van Dam, Feiner, and Hughes

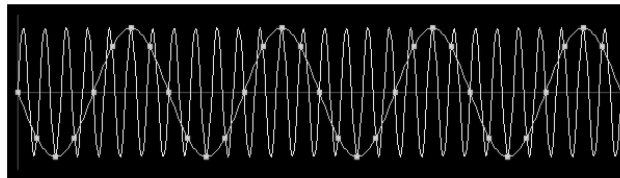
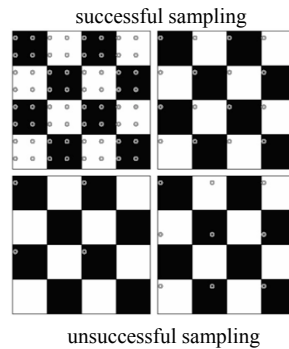
## Sampling and Aliasing

- Differences between continuous and discrete images
- Images are sampled version of a continuous brightness function.



## Sampling and Aliasing

- Sampling involves loss of information
- Aliasing: high spatial frequency components appear as low spatial frequency components in the sampled signal

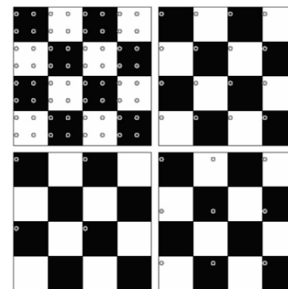


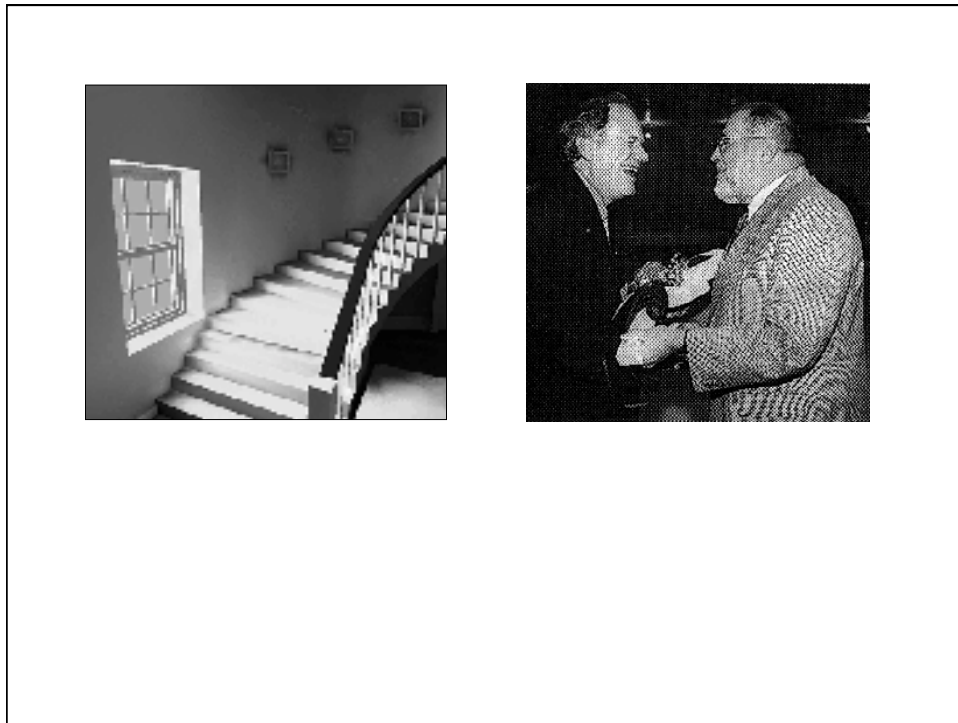
Input frequency: 7000 Hz Plot  Input signal  Grid  Sample points  Alias frequency?

Java applet from: <http://www.dsptutor.freeuk.com/aliasing/AD102.html>

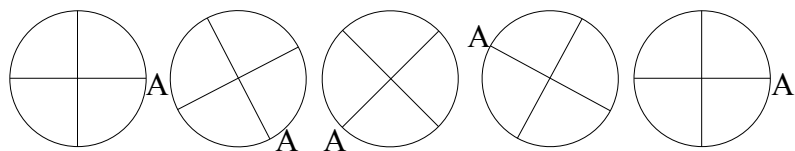
## Aliasing

- *Nyquist theorem*: The sampling frequency must be at least twice the highest frequency present for a signal to be reconstructed from a sampled version. (*Nyquist frequency*)





## Temporal Aliasing



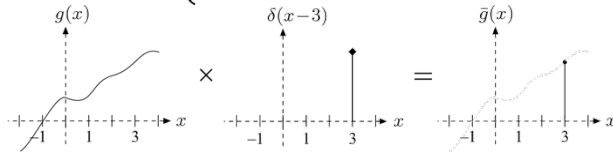
The wheel appears to be moving backwards at about  $\frac{1}{4}$  angular frequency

## Understanding the Sampling Process - Impulse function

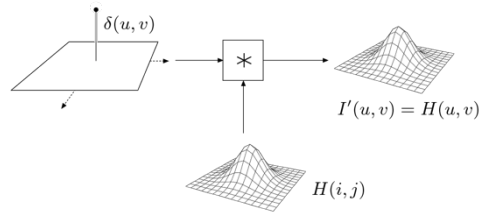
$$\delta(x) = 0 \text{ for } x \neq 0 \text{ and } \int_{-\infty}^{\infty} \delta(x) dx = 1$$

$$\delta(sx) = \frac{1}{|s|} \cdot \delta(x) \text{ for } s \neq 0$$

$$\bar{g}(x) = g(x) \cdot \delta(x - x_0) = \begin{cases} g(x_0) & \text{for } x = x_0 \\ 0 & \text{otherwise} \end{cases}$$

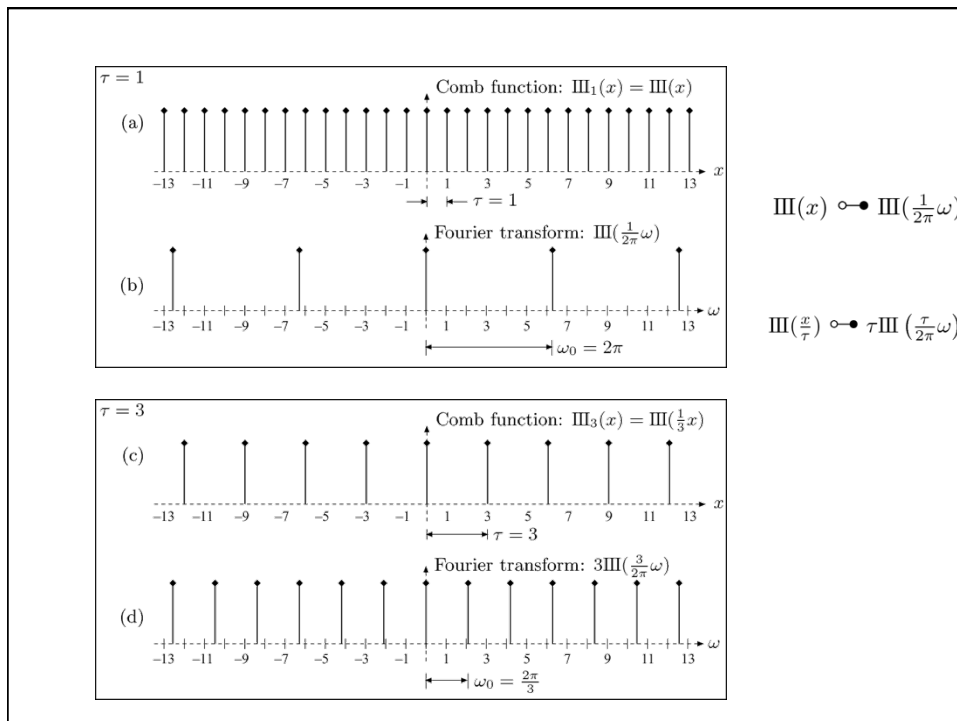
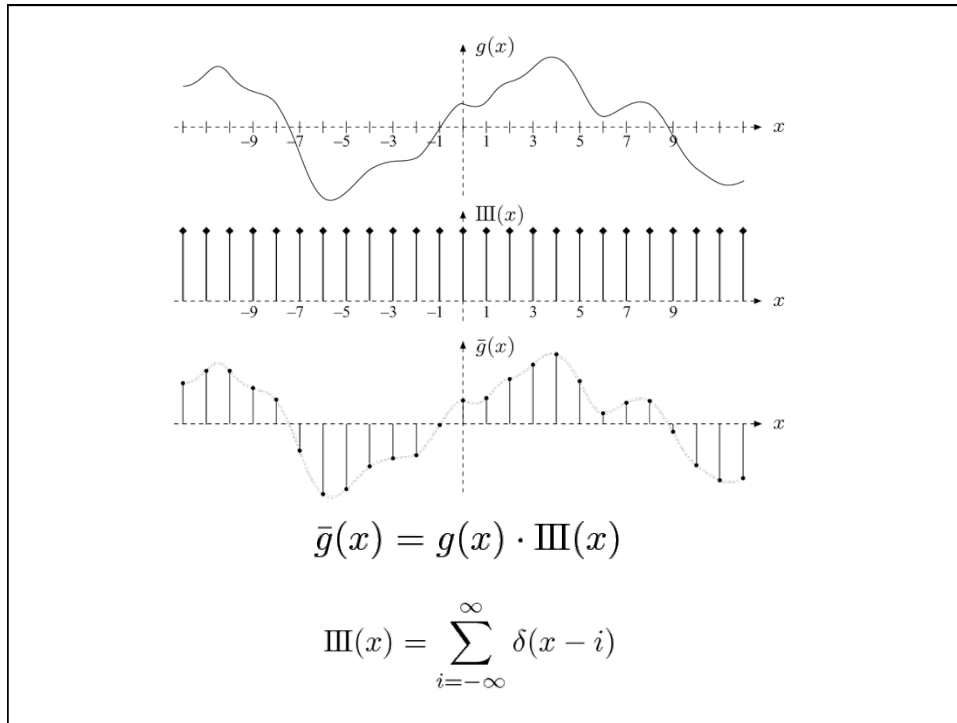


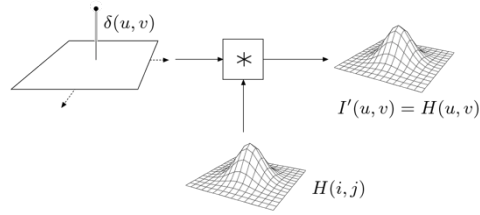
$$f(x) * \delta(x - d) = f(x - d)$$



$$f(x) * \delta(x - d) = f(x - d)$$

Convolving a function with an impulse at  $d$ , shifts the function to  $d$



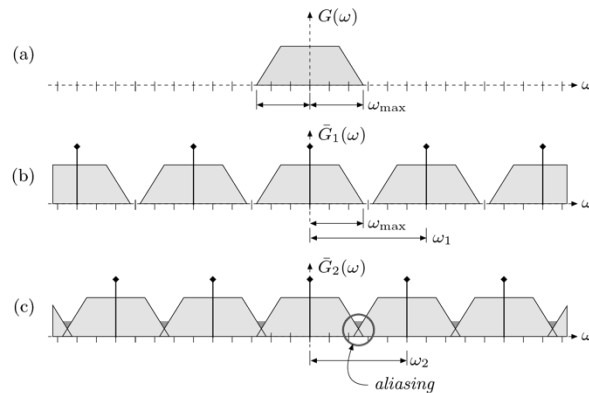


$$f(x) * \delta(x-d) = f(x-d)$$

$$\text{III}(x) = \sum_{i=-\infty}^{\infty} \delta(x-i)$$

$$f(x) * \text{III}(x) = \sum_{i=-\infty}^{\infty} f(x-i)$$

Convolving a function with an impulse at  $d$ , shifts the function to  $d$   
Convolving a function  $f$  with a comp function copies  $f$  at each impulse

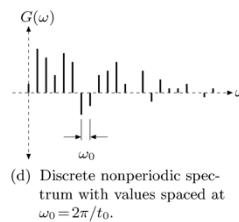
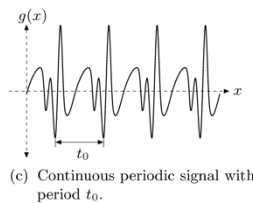
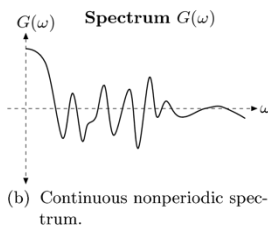
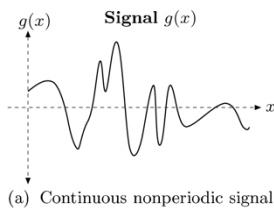
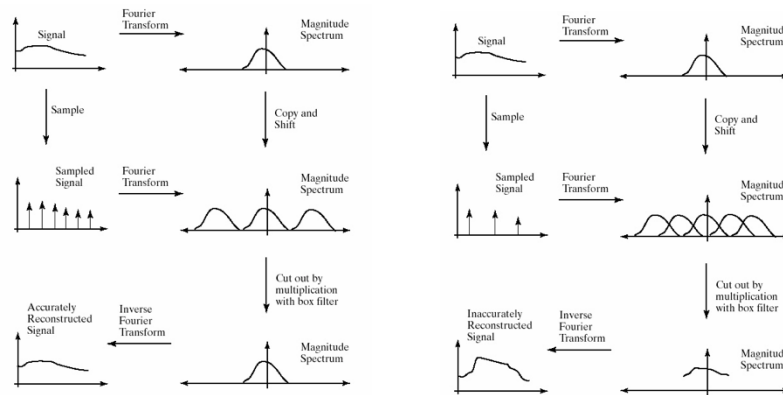


$$g(x) \cdot \text{III}\left(\frac{x}{\tau}\right) \circlearrowright G(\omega) * \tau \text{III}\left(\frac{\tau}{2\pi}\omega\right)$$

$$\omega_{\max} \leq \frac{1}{2}\omega_s \quad \text{OR} \quad \omega_s \geq 2\omega_{\max}$$

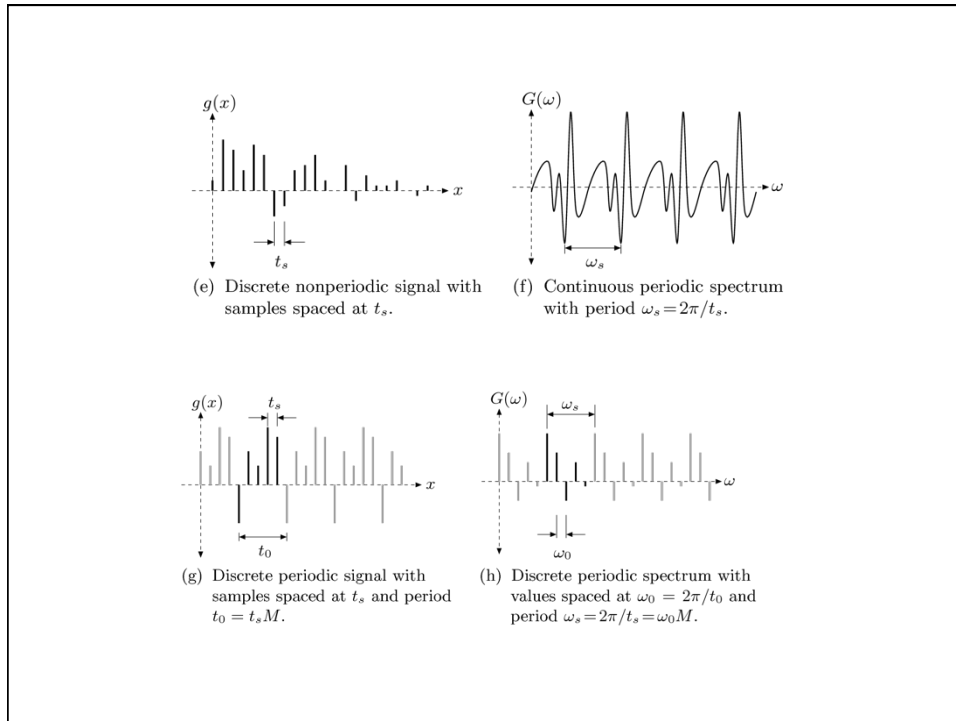
## Sampling, aliasing, and DFT

- DFT consists of a sum of copies of the FT of the original signal shifted by the sampling frequency:
  - If shifted copies do not intersect: reconstruction is possible.
  - If shifted copies do intersect: incorrect reconstruction, high frequencies are lost (Aliasing)



Recall Fourier series for periodic functions

$$g(x) = \sum_{k=0}^{\infty} [A_k \cos(k\omega_0 x) + B_k \sin(k\omega_0 x)]$$



## 2-dimension

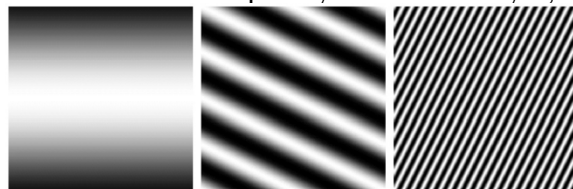
In two dimension

$$F(u, v) = \int \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi(ux+vy)} dx dy$$

$$f(x, y) = \int \int_{-\infty}^{\infty} F(u, v) e^{j2\pi(ux+vy)} du dv$$

$$e^{-j2\pi(ux+vy)} = \cos(2\pi(ux+vy)) + j \sin(2\pi(ux+vy))$$

- These terms are sinusoids on the x,y plane whose orientation and frequency are defined by u,v



## DFT in 2D

- For a 2D periodic function of size  $M \times N$ , DFT is defined as:

$$\begin{aligned}
 G(m, n) &= \frac{1}{\sqrt{MN}} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} g(u, v) \cdot e^{-i2\pi \frac{mu}{M}} \cdot e^{-i2\pi \frac{nv}{N}} \\
 &= \frac{1}{\sqrt{MN}} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} g(u, v) \cdot e^{-i2\pi \left( \frac{mu}{M} + \frac{nv}{N} \right)}
 \end{aligned}$$

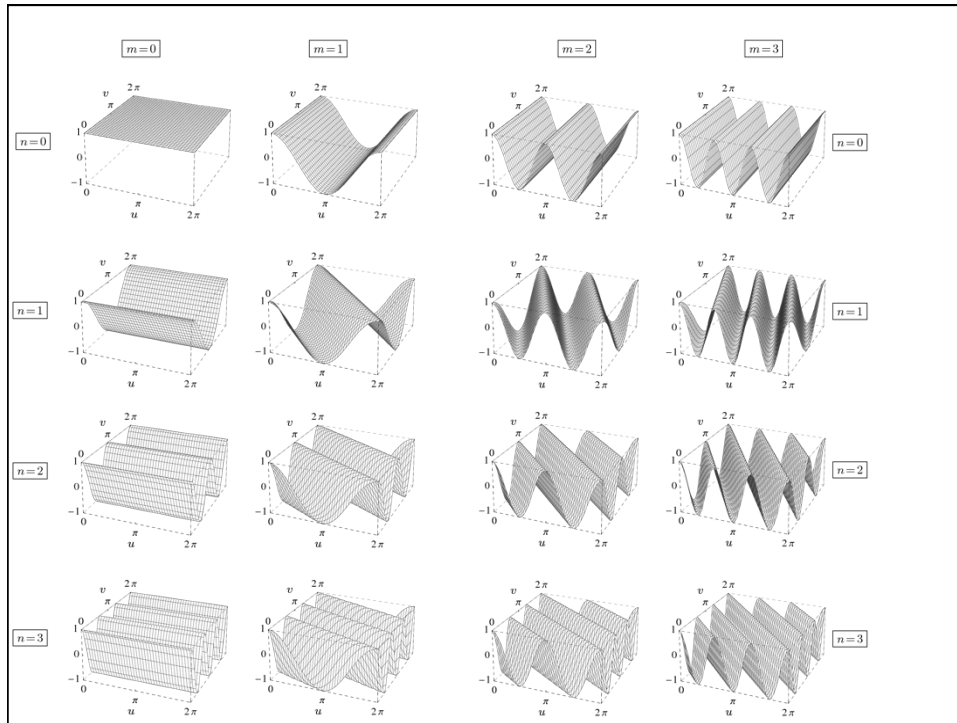
- Inverse transform

$$\begin{aligned}
 g(u, v) &= \frac{1}{\sqrt{MN}} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} G(m, n) \cdot e^{i2\pi \frac{mu}{M}} \cdot e^{i2\pi \frac{nv}{N}} \\
 &= \frac{1}{\sqrt{MN}} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} G(m, n) \cdot e^{i2\pi \left( \frac{mu}{M} + \frac{nv}{N} \right)}
 \end{aligned}$$

$$\begin{aligned}
 e^{i2\pi \left( \frac{mu}{M} + \frac{nv}{N} \right)} &= e^{i(\omega_m u + \omega_n v)} \\
 &= \underbrace{\cos \left[ 2\pi \left( \frac{mu}{M} + \frac{nv}{N} \right) \right]}_{\mathbf{C}_{m,n}^{M,N}(u, v)} + i \cdot \underbrace{\sin \left[ 2\pi \left( \frac{mu}{M} + \frac{nv}{N} \right) \right]}_{\mathbf{S}_{m,n}^{M,N}(u, v)}
 \end{aligned}$$

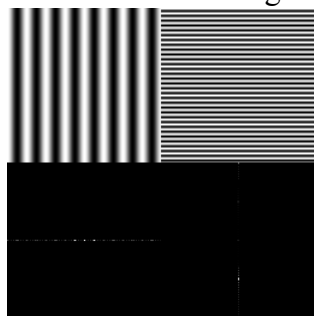
$$\mathbf{C}_{m,n}^{M,N}(u, v) = \cos \left[ 2\pi \left( \frac{mu}{M} + \frac{nv}{N} \right) \right] = \cos(\omega_m u + \omega_n v)$$

$$\mathbf{S}_{m,n}^{M,N}(u, v) = \sin \left[ 2\pi \left( \frac{mu}{M} + \frac{nv}{N} \right) \right] = \sin(\omega_m u + \omega_n v)$$



## Visualizing 2D-DFT

- The FT tries to represent all images as a summation of cosine-like images



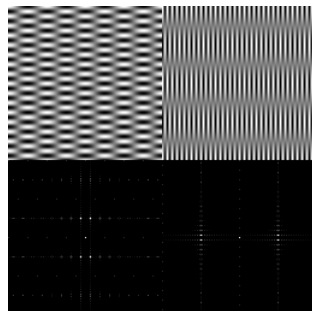
← Images of pure cosines

- *Center of the image*: the origin of the frequency coordinate system
- *m-axis*: (left to right) the horizontal component of frequency
- *n-axis*: (bottom-top) the vertical component of frequency
- Center dot (0,0) frequency : image average

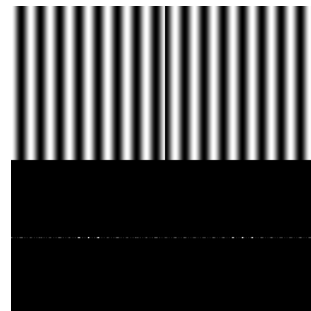
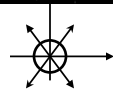
← FT

- high frequencies in the vertical direction will cause bright dots away from the center in the vertical direction.
- high frequencies in the horizontal direction will cause bright dots away from the center in the horizontal direction.

- Since images are real numbers (not complex) FT image is symmetric around the origin.

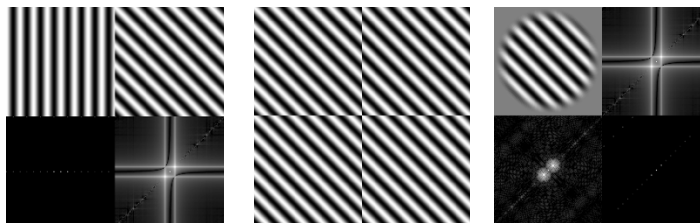


FT: symmetry



FT is shift invariant

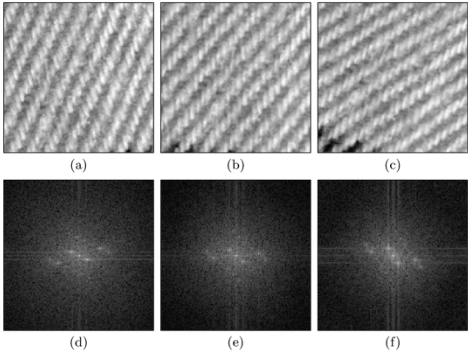
- In general, rotation of the image results in equivalent rotation of its FT



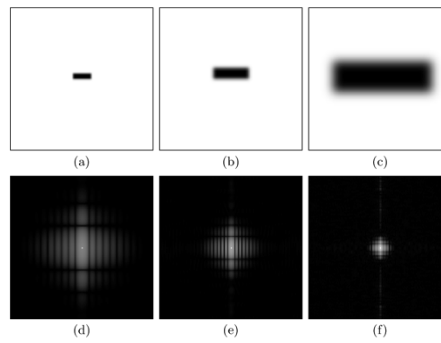
Why it is not the case ?

- Edge effect !
- FT always treats an image as if it were part of a periodically replicated array of identical images extending horizontally and vertically to infinity
- Solution: “windowing” the image

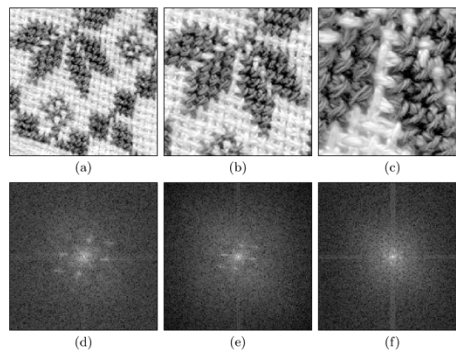
# Rotation



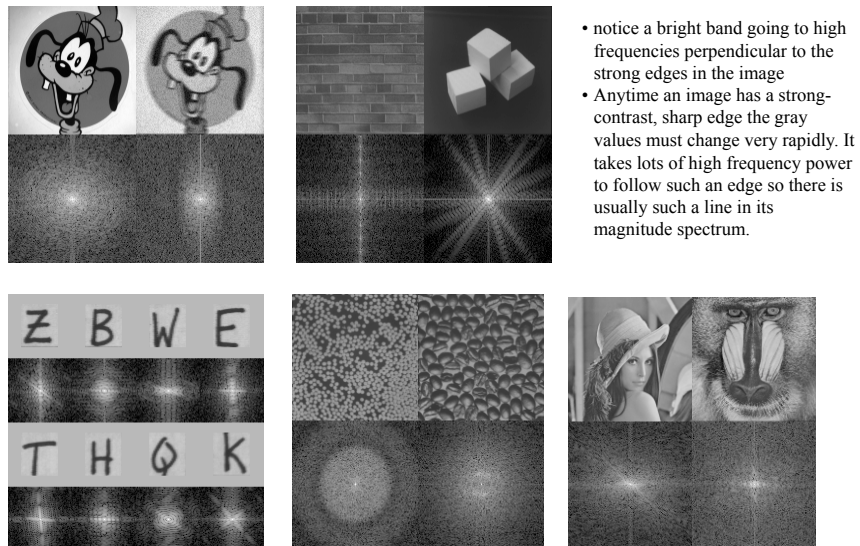
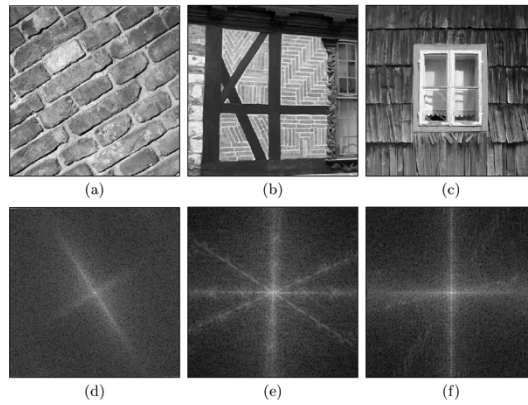
## Scaling



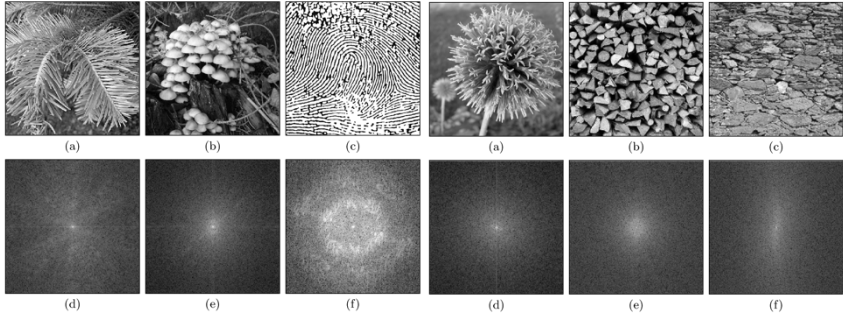
## Periodic image patterns



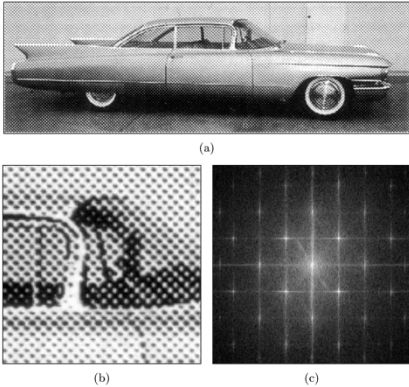
## Oriented, elongated structures



### Natural Images



### Print patterns



## Linear Filters in Frequency space

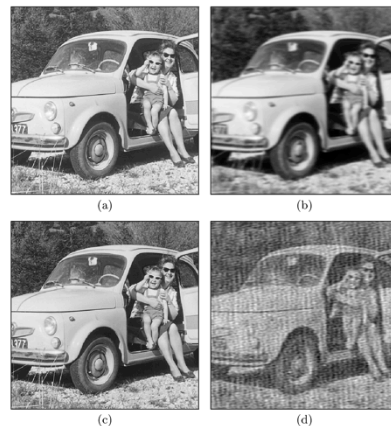
$$\begin{array}{ccccc} \text{Image space: } g(u, v) * h(u, v) & = & g'(u, v) & & \\ \downarrow \text{DFT} & & \downarrow \text{DFT} & & \uparrow \text{DFT}^{-1} \\ \text{Frequency space: } G(m, n) \cdot H(m, n) & \longrightarrow & G'(m, n) & & \end{array}$$

## Inverse Filters - De-convolution

- How can we remove the effect of a filter ?

$$g_{\text{blur}} = g_{\text{orig}} * h_{\text{blur}}$$

$$G_{\text{blur}} = G_{\text{orig}} \cdot H_{\text{blur}}$$



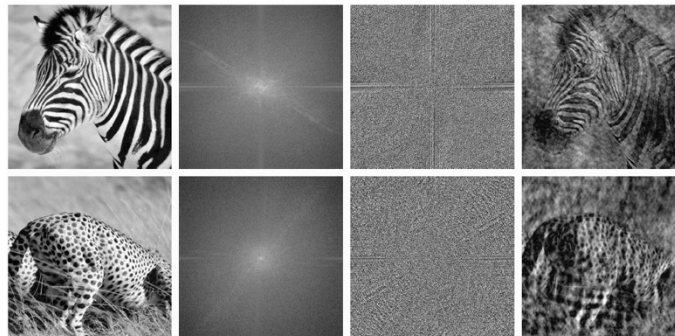
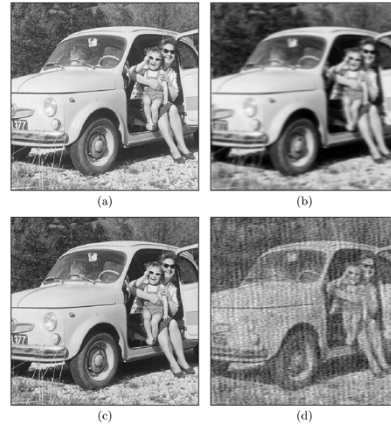
## Inverse Filters - De-convolution

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$$G_{\text{blur}} = G_{\text{orig}} \cdot H_{\text{blur}}$$

$$G_{\text{orig}}(m, n) = \frac{G_{\text{blur}}(m, n)}{H_{\text{blur}}(m, n)}$$



- What happens if we swap the magnitude spectra ?
- Phase spectrum holds the spatial information (where things are),
- Phase spectrum is more important for perception than magnitude spectrum.

## The Discrete Cosine Transform (DCT)

- FT and DFT are designed for processing complex-valued signal and always produce a complex-valued spectrum.
- For a real-valued signal, the Fourier spectrum is symmetric
- Discrete Cosine Transform (DCT): similar to DFT but does not work with complex signals.
- DCT uses cosine functions only, with various wave numbers as the basis functions and operates on real-valued signals

