

CS334: Digital Imaging and Multimedia

Multimedia Digitization

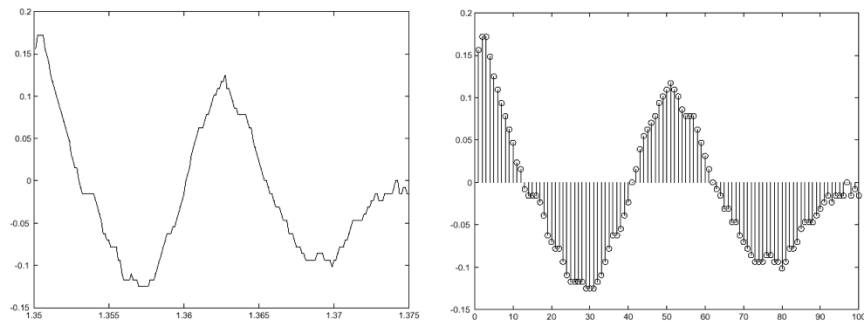
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Outlines

- Digitizing Signals and Images
- Image histograms and its applications

- Sources:
 - Havaladar and Medioni “Multimedia Systems” Ch 2
 - Burger and Burge “Digital Image Processing” Ch. 2 and Ch. 4

Analog to Digital



Advantage of Digital over Analog

- Easy to random access and interact with: group of pixel, or a section of a sound track.
- Different processing can be applied
- Stored digital signal do not degrade over time
- Digital data can be efficiently compressed
- Unified representation of all media types, audio, images, video, ...

Issues

- Sampling
- Quantization
- Bit Rate

Sampling

- $x_s(n) = x(nT)$, where T is the sampling period
- $F = 1/T$ is the sampling frequency
- In reality, more complex, as sampling comes with filtering

Surprisingly, we may not lose information in sampling

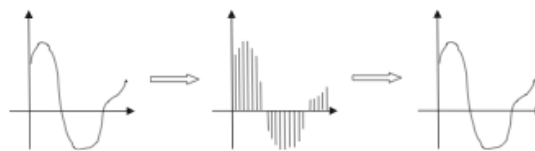


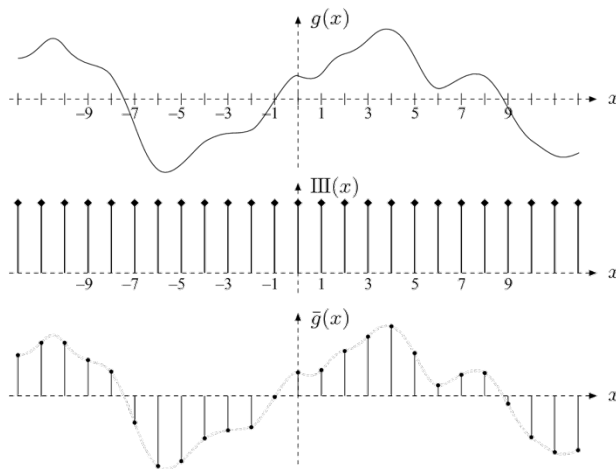
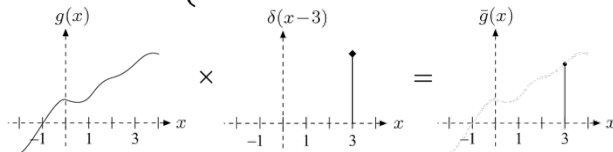
Figure 2-2 Analog-to-digital conversion and the corresponding interpolation from the digital-to-analog domain

Impulse function

$$\delta(x) = 0 \text{ for } x \neq 0 \text{ and } \int_{-\infty}^{\infty} \delta(x) dx = 1$$

$$\delta(sx) = \frac{1}{|s|} \cdot \delta(x) \text{ for } s \neq 0$$

$$\bar{g}(x) = g(x) \cdot \delta(x - x_0) = \begin{cases} g(x_0) & \text{for } x = x_0 \\ 0 & \text{otherwise} \end{cases}$$



$$\bar{g}(x) = g(x) \cdot \text{III}(x)$$

$$\text{III}(x) = \sum_{i=-\infty}^{\infty} \delta(x - i) \quad \text{Comb function}$$

Quantization

- **quantization** is the process of approximating a continuous range of values (or a very large set of possible discrete values) by a relatively-small set of discrete symbols or integer values.
- Irreversible and lossy
 $x_q(n) = Q[x_s(n)]$, Q is a rounding function

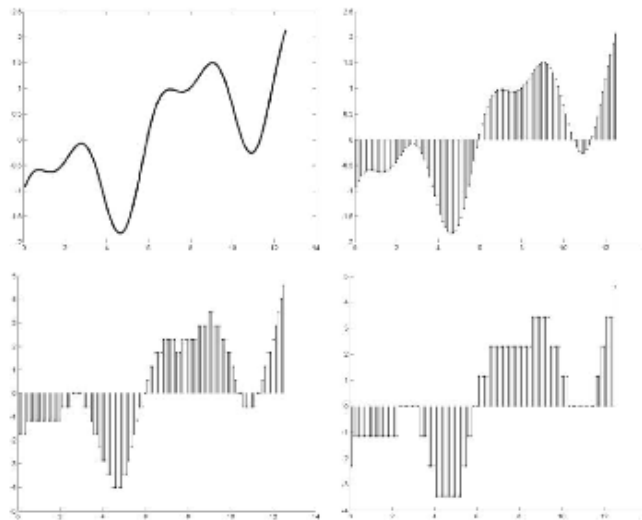
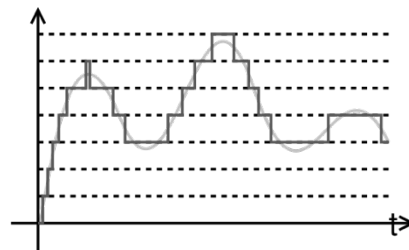
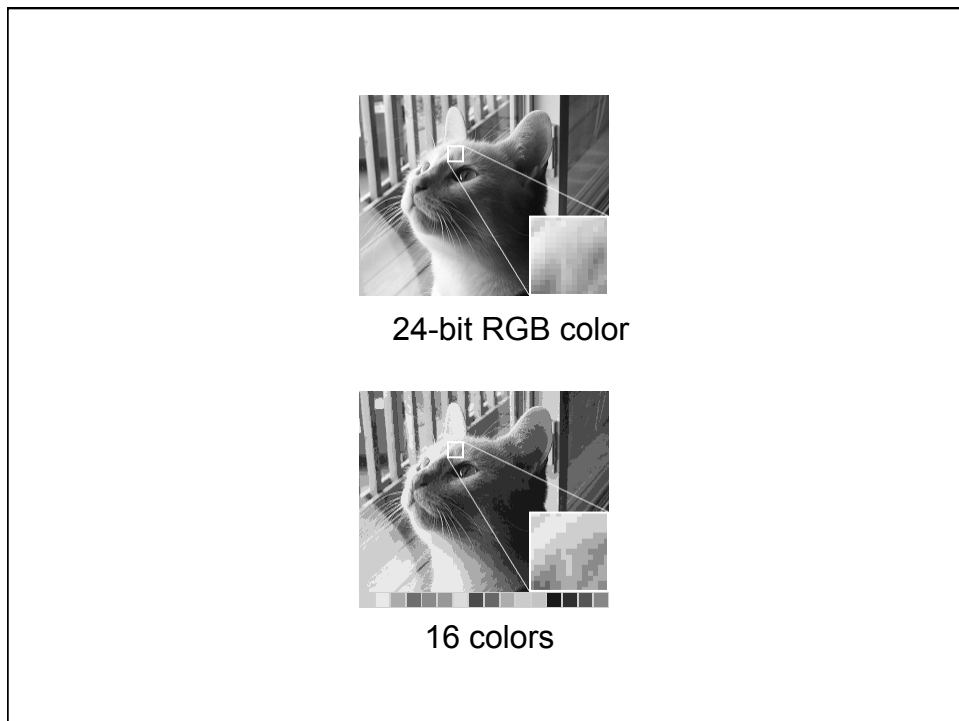
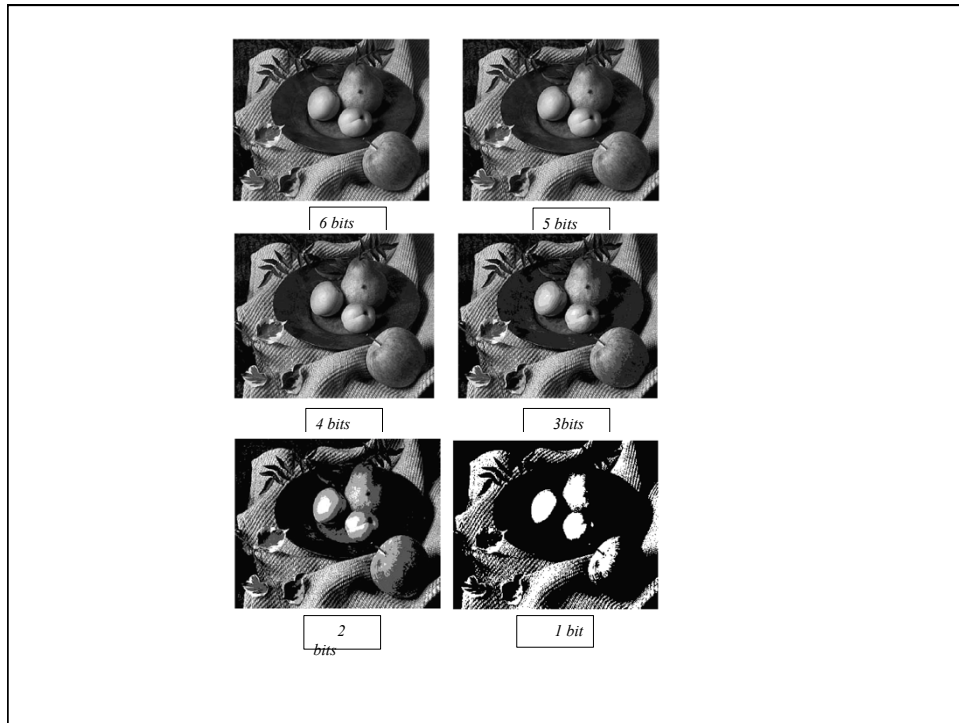


Figure 2-3 Original analog signal (upper left) is shown sampled and quantized at different quantization levels. For quantization, 8 bits (256 levels), 4 bits (16 levels), and 3 bits (8 levels) were used to produce the digital signals on the top right, bottom left, and bottom right, respectively.



Bit Rate

Bit Rate = *Sampling rate* \times *Quantization per sample* (bits/second)

Audio (MP3)

- 32 kbit/s — MW (AM) quality
- 96 kbit/s — FM quality
- 128–160 kbit/s — Standard Bitrate quality; difference can sometimes be obvious (e.g. bass quality 192 kbit/s — DAB (Digital Audio Broadcasting) quality. Quickly becoming the new 'standard' bitrate for MP3 music; difference can be heard by few people
- 224–320 kbit/s — Near CD quality. Sound is nearly indistinguishable from most CDs.

Other audio

- 800 bit/s — minimum necessary for recognizable speech (using special-purpose ES-1015 speech codecs)
- 8 kbit/s — telephone quality (using speech codecs)
- 500 kbit/s–1 Mbit/s — lossless audio
- 1411 kbit/s — PCM sound format of Compact Disc Digital Audio

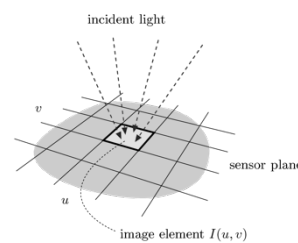
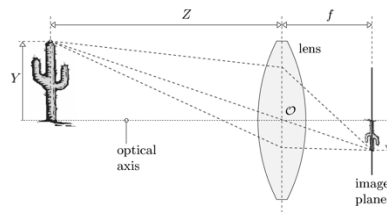
Video (MPEG2)

- 16 kbit/s — videophone quality (minimum necessary for a consumer-acceptable "talking head" picture)
- 128 – 384 kbit/s — business-oriented videoconferencing system quality
- 1.25 Mbit/s — VCD quality
- 5 Mbit/s — DVD quality
- 15 Mbit/s — HDTV quality
- 36 Mbit/s — HD DVD quality
- 54 Mbit/s — Blu-ray Disc quality

Signal	Sampling rate	Quantization	Bit rate
Speech	8 KHz	8 bits per sample	64 Kbps
Audio CD	44.1 KHz	16 bits per sample	706 Kbps (mono) 1.4 Mbps (stereo)
Teleconferencing	16 KHz	16 bits per sample	256 Kbps
AM Radio	11 KHz	8 bits per sample	88 Kbps
FM Radio	22 KHz	16 bits per sample	352 Kbps (mono) 704 Kbps (stereo)
NTSC TV image frame	Width – 486 Height – 720	16 bits per sample	5.6 Mbits per frame
HDTV (1080i)	Width – 1920 Height – 1080	12 bits per pixel on average	24.88 Mbits per frame

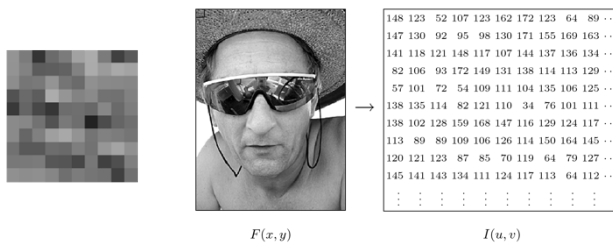
Digitizing images

- What is projected on the image plan is a distribution of light energy that is:
 - Two-dimensional
 - Time-dependent
 - Continuous
- To go digital:
 - Spatial sampling
 - Temporal sampling
 - Quantization of pixel values

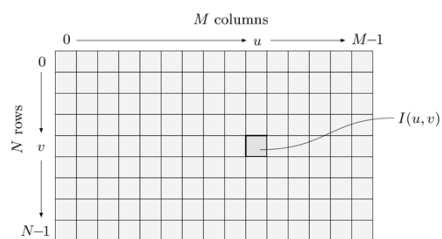


- Digital image: two-dimensional, ordered matrix of integers, i.e., a two-dimensional function of integer coordinates $N \times N$ that maps a range of image values P

$$I(u, v) \in \mathbb{P} \quad \text{and} \quad u, v \in \mathbb{N}.$$



- Image resolution: number of image elements per measurement.
- Image coordinate system



Grayscale (Intensity Images):

Chan.	Bits/Pix.	Range	Use
1	1	0..1	Binary image: document, illustration, fax
1	8	0..255	Universal: photo, scan, print
1	12	0..4095	High quality: photo, scan, print
1	14	0..16383	Professional: photo, scan, print
1	16	0..65535	Highest quality: medicine, astronomy

Color Images:

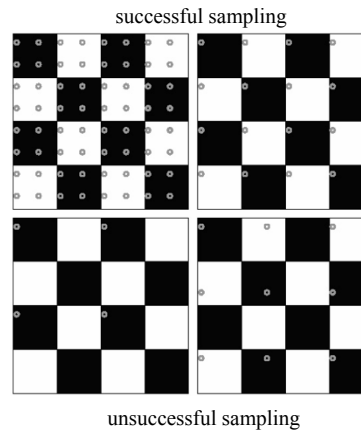
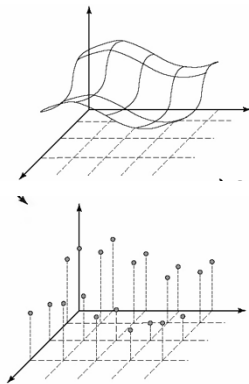
Chan.	Bits/Pix.	Range	Use
3	24	$[0..255]^3$	RGB, universal: photo, scan, print
3	36	$[0..4095]^3$	RGB, high quality: photo, scan, print
3	42	$[0..16383]^3$	RGB, professional: photo, scan, print
4	32	$[0..255]^4$	CMYK, digital prepress

Special Images:

Chan.	Bits/Pix.	Range	Use
1	16	-32768..32767	Whole numbers pos./neg., increased range
1	32	$\pm 3.4 \cdot 10^{38}$	Floating point: medicine, astronomy
1	64	$\pm 1.8 \cdot 10^{308}$	Floating point: internal processing

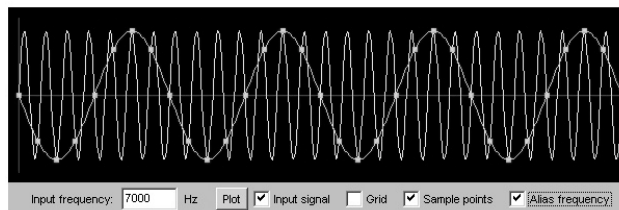
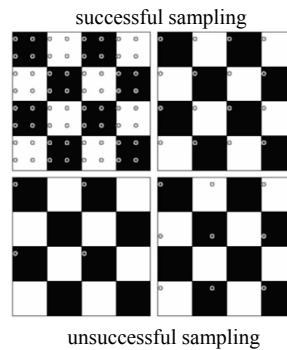
Sampling and Aliasing

- Images are sampled version of a continuous brightness function.



Sampling and Aliasing

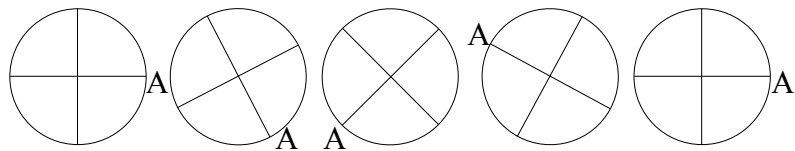
- Sampling involves loss of information
- Aliasing: high frequency components appear as low frequency components in the sampled signal



Java applet from: <http://www.dsptutor.freeuk.com/aliasing/AD102.html>



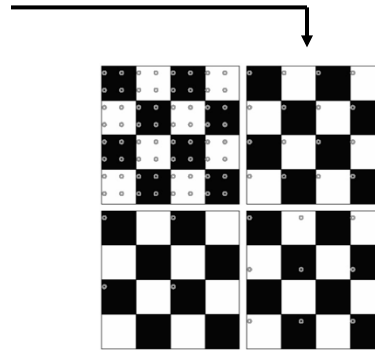
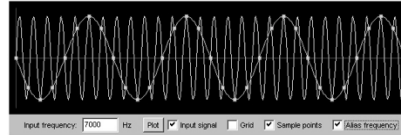
Temporal Aliasing



The wheel appears to be moving backwards at about $\frac{1}{4}$ angular frequency

Aliasing

- *Nyquist theorem*: The sampling frequency must be at least twice the highest frequency present for a signal to be reconstructed from a sampled version. (*Nyquist frequency*)

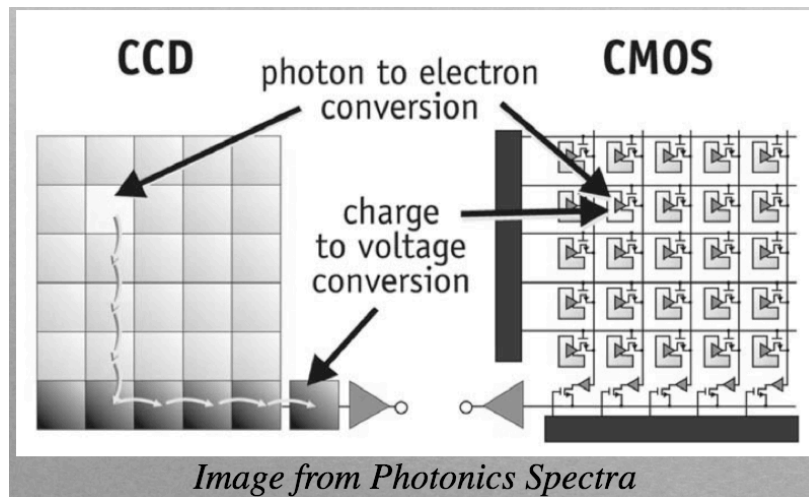
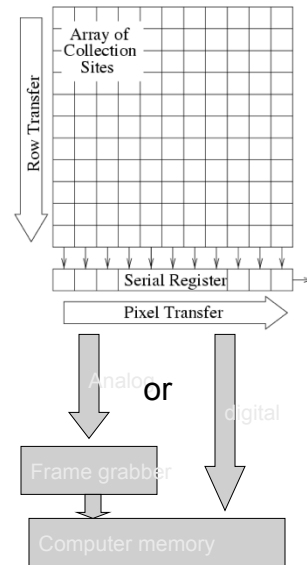
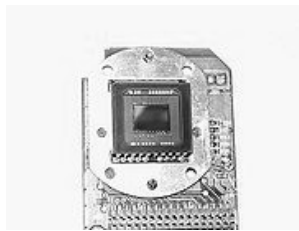


CCD & CMOS

- CCD Cameras (Charge Couple Device) (1970)
 - Accumulate signal charge in each pixel proportional to the local illumination intensity
 - CCD transfers each pixel's charge packet sequentially to convert its charge to a voltage
- CMOS Cameras (Complementary Metal Oxide Silicon)
 - Accumulate signal charge in each pixel proportional to the local illumination intensity
 - The charge-to-voltage conversion takes place in each pixel

CCD cameras

- Charge-coupled device CCD
- Image is read one row at a time
- This process is repeated several times per second (frame rate)



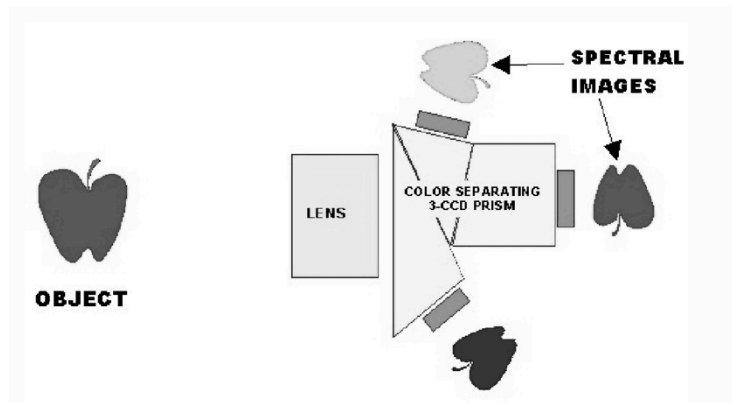
<i>CMOS</i>	<i>CCD</i>
<ul style="list-style-type: none">◦ <i>Easier to manufacture</i>◦ <i>Camera-on-a-chip</i>◦ <i>Lower power consumption</i>◦ <i>Smaller sensor</i>◦ <i>Higher speeds</i>◦ <i>Selective ROI windowing</i>◦ <i>Natural anti-blooming</i>	<ul style="list-style-type: none">◦ <i>Higher fill factor</i>◦ <i>Smaller noise</i>◦ <i>Smaller dark current</i>◦ <i>Better pixel uniformity</i>◦ <i>Better dynamic range</i>◦ <i>Non-rolling electronic shutter</i>

Check out: CCD vs. CMOS: Facts and Fiction by
Dave Litwiller, in Photonics Spectra, January
2001

Color cameras

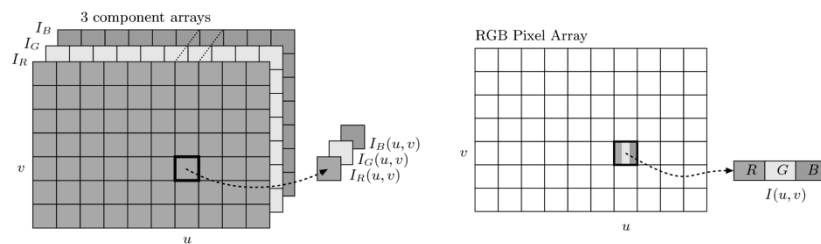
- Two types of color cameras
 - Single CCD array
 - in front of each CCD element is a filter - red, green or blue
 - color values at each pixel are obtained by hardware interpolation
 - subject to artifacts
 - lower intensity quality than a monochromatic camera
 - similar to human vision
 - 3 CCD arrays packed together, each sensitive to different wavelengths of light

3 CCD cameras



RGB representation

- True color images: represent each pixel with its R,G,B values.
 - Component ordering
 - Packed ordering



```

1 int c = ip.getPixel(u,v); // a color pixel
2 int r = (c & 0xff0000) >> 16; // red value
3 int g = (c & 0x00ff00) >> 8; // green value
4 int b = (c & 0x0000ff); // blue value

1 int[] RGB = new int[3];
2 ...
3 RGB = ip.getPixel(u,v,RGB);
4 int r = RGB[0];
5 int g = RGB[1];
6 int b = RGB[2];
7 ...
8 ip.putPixel(u,v,RGB);
                
```

RGB representation

- Alternative representation: Indexed images:
 - make a color table
 - each pixel's color is represented by its color's index in the table
- Advantages?
- Limitations?

Image $I_{idx(u,v)}$

Index	P_R	P_G	P_B
0	r_0	g_0	b_0
1	r_1	g_1	b_1
2	r_2	g_2	b_2
⋮	⋮	⋮	⋮
k	r_k	g_k	b_k
⋮	⋮	⋮	⋮
$N-1$	r_{N-1}	g_{N-1}	b_{N-1}

Color Table P